Forklift Starter and Alternator

Forklift Starters and Alternators - A starter motors today is usually a permanent-magnet composition or a series-parallel wound direct current electrical motor along with a starter solenoid mounted on it. Once current from the starting battery is applied to the solenoid, basically through a key-operated switch, the solenoid engages a lever which pushes out the drive pinion that is situated on the driveshaft and meshes the pinion with the starter ring gear that is found on the engine flywheel.

The solenoid closes the high-current contacts for the starter motor, that begins to turn. Once the engine starts, the key operated switch is opened and a spring within the solenoid assembly pulls the pinion gear away from the ring gear. This particular action causes the starter motor to stop. The starter's pinion is clutched to its driveshaft by means of an overrunning clutch. This allows the pinion to transmit drive in only a single direction. Drive is transmitted in this way via the pinion to the flywheel ring gear. The pinion continuous to be engaged, like for instance for the reason that the operator did not release the key as soon as the engine starts or if there is a short and the solenoid remains engaged. This actually causes the pinion to spin independently of its driveshaft.

The actions mentioned above will stop the engine from driving the starter. This vital step prevents the starter from spinning very fast that it will fly apart. Unless adjustments were done, the sprag clutch arrangement will preclude using the starter as a generator if it was employed in the hybrid scheme mentioned prior. Normally a regular starter motor is meant for intermittent utilization that would stop it being used as a generator.

Hence, the electrical parts are designed to function for just about under 30 seconds so as to avoid overheating. The overheating results from very slow dissipation of heat due to ohmic losses. The electrical parts are intended to save cost and weight. This is truly the reason the majority of owner's guidebooks for vehicles recommend the operator to pause for a minimum of ten seconds after each ten or fifteen seconds of cranking the engine, when trying to start an engine which does not turn over at once.

In the early part of the 1960s, this overrunning-clutch pinion arrangement was phased onto the market. Before that time, a Bendix drive was used. The Bendix system functions by placing the starter drive pinion on a helically cut driveshaft. Once the starter motor begins turning, the inertia of the drive pinion assembly allows it to ride forward on the helix, therefore engaging with the ring gear. When the engine starts, the backdrive caused from the ring gear allows the pinion to exceed the rotating speed of the starter. At this moment, the drive pinion is forced back down the helical shaft and thus out of mesh with the ring gear.

During the 1930s, an intermediate development between the Bendix drive was made. The overrunning-clutch design that was made and launched in the 1960s was the Bendix Folo-Thru drive. The Folo-Thru drive has a latching mechanism along with a set of flyweights in the body of the drive unit. This was a lot better because the average Bendix drive utilized so as to disengage from the ring when the engine fired, even if it did not stay running.

As soon as the starter motor is engaged and begins turning, the drive unit is forced forward on the helical shaft by inertia. It then becomes latched into the engaged position. Once the drive unit is spun at a speed higher than what is achieved by the starter motor itself, for example it is backdriven by the running engine, and after that the flyweights pull outward in a radial manner. This releases the latch and allows the overdriven drive unit to become spun out of engagement, therefore unwanted starter disengagement could be prevented before a successful engine start.